## Description

The AP8802H is a step-down DC/DC converter designed to drive LEDs with a constant current. The device can drive up to thirteen LEDs, depending on the forward voltage of the LEDs, in series from a voltage source of 8 V to 60 V . Series connection of the LEDs provides identical LED currents resulting in uniform brightness and eliminating the need for ballast resistors. The AP8802H switches at frequency up to 700 kHz . This allows the use of small size external components, hence minimizing the PCB area needed.
Maximum output current of AP8802H is set via an external resistor connected between the $\mathrm{V}_{\mathrm{IN}}$ and SET input pins. Dimming is achieved by applying either a DC voltage or a PWM signal at the CTRL input pin. An input voltage of 0.2 V or lower at CTRL shuts down the output at SW and puts the device into a low-current standby state.

## Features

- LED driving current up to 1 A
- High efficiency up to $95 \%$
- Operating input voltage up to 60 V
- 5\% nominal accuracy
- High switching frequency up to 700 kHz
- PWM/DC input for dimming control
- Built-in output open-circuit protection
- SO-8EP is available in "Green" Molding Compound (No Br, Sb)
- Totally Lead-Free \& Fully RoHS Compliant (Notes 1 \& 2)
- Halogen and Antimony Free. "Green" Device (Note 3)


## Pin Assignments



## Applications

- Commercial \& industrial lighting
- Small LCD panel backlight
- Appliances interior lighting
- Architecture Detail lighting

Notes: 1. No purposely added lead. Fully EU Directive 2002/95/EC (RoHS) \& 2011/65/EU (RoHS 2) compliant.
2. See http://www.diodes.com for more information about Diodes Incorporated's definitions of Halogen- and Antimony-free, "Green" and Lead-free.
3. Halogen- and Antimony-free "Green" products are defined as those which contain <900ppm bromine, <900ppm chlorine ( $<1500 \mathrm{ppm}$ total $\mathrm{Br}+\mathrm{Cl}$ ) and <1000ppm antimony compounds.

## Typical Application Circuit



## Pin Descriptions

| Pin Name | Function |
| :---: | :---: |
| SW | Switch Pin. Connect inductor/freewheeling diode here, minimizing track length at this pin to reduce EMI. |
| GND | GND pin |
| SET | Set Nominal Output Current Pin. Configure the output current of the device. |
| CTRL | Dual function dimming control pin with an input impedance approximately $50 \mathrm{k} \Omega$. <br> - Input voltage of 0.2 V or lower forces the device into low current standby mode and shuts off the output. <br> - A PWM signal (driven by an open-drain/collector source) allows the output current to be adjusted over a wide range up to $100 \%$. <br> - An analog voltage between 0.3 V and 2.5 V adjusts the output current between $24 \%$ and $200 \%$ of the current set by $0.2 \mathrm{~V} / \mathrm{R}_{\mathrm{s}}$. <br> If the CTRL pin is left open then its voltage will default to $\mathrm{V}_{\text {REF }}$ |
| V IN | Input Supply Pin. Must be locally bypassed. |
| EP | Exposed pad: Internally connected to IC substrate. It should be connected to GND and as large as possible thermal mass for improved thermal impedance and power dissipation capability. See Land Pad diagrams. |
| NC | No connection |

## Functional Block Diagram



Figure. 1 Functional Block Diagram

## Absolute Maximum Ratings (Note 4)

| Symbol | Parameter | Rating | Unit |
| :---: | :--- | :---: | :---: |
| $\mathrm{V}_{\text {IN }}$ | $\mathrm{V}_{\text {IN }}$ pin Voltage | -0.3 to +65 | V |
| $\mathrm{~V}_{\text {SW }}$ | SW Voltage | -0.3 to +65 | V |
| $\mathrm{~V}_{\text {CTRL }}$ | CTRL Pin Input Voltage | -0.3 to +6 | V |
| $\mathrm{~V}_{\text {SENSE }}$ | SET Voltage (Note 5) | +0.3 to -5 | V |
| $\mathrm{~T}_{\mathrm{J}}$ | Junction Temperature | 150 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\text {LEAD }}$ | Lead Temperature Soldering | 300 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\text {ST }}$ | Storage Temperature Range | -65 to +150 | ${ }^{\circ} \mathrm{C}$ |

Note: $\quad 4$ All voltages unless otherwise stated are measured with respect to GND.
5. $\mathrm{V}_{\text {SENSE }}$ is measured with respect to $\mathrm{V}_{\text {IN }}$.

Caution: Stresses greater than the 'Absolute Maximum Ratings' specified above, may cause permanent damage to the device. These are stress ratings only; functional operation of the device at conditions between maximum recommended operating conditions and absolute maximum ratings is not implied. Device reliability may be affected by exposure to absolute maximum rating conditions for extended periods of time.

Semiconductor devices are ESD sensitive and may be damaged by exposure to ESD events. Suitable ESD precautions should be taken when handling and transporting these devices.

## Recommended Operating Conditions

| Symbol | Parameter | Min | Max | Unit |
| :---: | :--- | :---: | :---: | :---: |
| $\mathrm{V}_{\text {IN }}$ | Operating Input Voltage relative to GND | 8.0 | 60.0 | V |
| $\mathrm{~V}_{\text {CTRLDC }}$ | Voltage range for 24\% to 200\% DC dimming relative to GND (Note 6) | 0.3 | 2.5 | V |
| $\mathrm{~V}_{\text {CTRLL }}$ | Voltage Low for PWM dimming relative to GND | 0 | 0.2 | V |
| $\mathrm{f}_{\text {OSC }}$ | Maximum Switching Frequency (Note 7) | - | 625 | kHz |
| $\mathrm{T}_{\mathrm{A}}$ | Ambient Temperature Range | -40 | +125 | ${ }^{\circ} \mathrm{C}$ |
| Duty Cycle | Using Inductor $\geq 100 \mu \mathrm{H}$ (Note 8) | 0.10 | 0.95 | - |

Notes: $\quad 6$. For $100 \%$ brightness either leave floating or connect to 1.25 V relative to GND.
7. AP8802H will operate at higher frequencies but accuracy will be affected due to propagation delays.
8. For most applications the LED current will be within $5 \%$ over the duty cycle range specified. Duty cycle accuracy is also dependent on propagation delay. Smaller size inductors can be used but LED current accuracy may be greater than $8 \%$ at extremes of duty cycle. This is most noticeable at low duty cycles (less than 0.1) or when the input voltage is high and only one LED is being driven.

## Electrical Characteristics ( $\mathrm{V}_{\mathrm{IN}}=12 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise specified.)

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| lout | Continuous switch current | (Note 9) | - | - | 1 | A |
| le | Quiescent Current |  | - | 75 | 120 | $\mu \mathrm{A}$ |
| $\mathrm{V}_{\text {THD }}$ | Internal Threshold Voltage |  | 190 | 200 | 210 | mV |
| $\mathrm{V}_{\text {SENSEHYS }}$ | Sense threshold hysteresis |  | - | 15 | - | \% |
| SET | SET pin input current | $\mathrm{V}_{\text {SET }}=\mathrm{V}_{\text {IN }}-0.2$ | - | 5 | - | $\mu \mathrm{A}$ |
| $V_{\text {REF }}$ | Internal Reference Voltage |  | - | 1.25 | - | V |
| RDS(ON) | On Resistance of MOSFET | Isw $=0.8 \mathrm{~A}$ | - | 0.65 | 1.10 | $\Omega$ |
| Isw_leakage | Switch leakage current |  | - | - | 8 | $\mu \mathrm{A}$ |
| $\theta_{\text {JA }}$ | Thermal Resistance Junction-to-Ambient | SO-8EP (Note 10) | - | 45 | - | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| $\theta_{\text {Jc }}$ | Thermal Resistance Junction-to-Case | SO-8EP (Note 10) | - | 7 | - | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |

Notes: $\quad 9$. Refer to figure 8 for the device derating curve.
10. Test condition for SO-8EP: Device mounted on FR-4 PCB, $2^{\prime \prime} \times 2^{\prime \prime}, 2$ oz copper, minimum recommended pad layout on top layer and thermal vias to bottom layer ground plane. See Land pad diagram For better thermal performance, larger copper pad for heat-sink is needed.

## Typical Characteristics



INPUT VOLTAGE (V)
Figure. 2 Supply Current (not switching) vs. Input Voltage


Figure. $4 \mathrm{R}_{\mathrm{DS}(\mathrm{ON})}$ vs. Ambient Temperature


Figure. 6 LED Current vs. $V_{\text {CTRL }}$


Figure. $3 \mathrm{~V}_{\text {CTRL }}$ vs. Ambient Temperature


Figure. 5 LED Current vs. $\mathrm{R}_{\mathrm{SET}}$


Figure. 7 Switching Frequency vs. $\mathrm{V}_{\text {CTRL }}$

## Typical Characteristics ( $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{IN}}=60 \mathrm{~V}, \mathrm{~L}=68 \mu \mathrm{H}$; unless otherwise stated.)



Figure. 8 LED Current vs. Input Voltage


Figure. 10 Switching Frequency vs. Input Voltage


Figure. 12 Steady State Waveforms


Figure. 9 Efficiency vs. Input Voltage


Figure. 11 Duty Cycle vs. Input Voltage


Figure. 13 Start-Up Showing LED Current Soft Start

## Application Information

## LED Current Control

The LED current is controlled by the resistor $\mathrm{R}_{\text {SET }}$ in Figure 14 connected between $\mathrm{V}_{\mathrm{IN}}$ and SET . The nominal average output current in the LED(s) with the CTRL pin open circuit is defined as:


Figure. 14 Typical Application Circuit

## Inductor Selection

This section highlights how to select the inductor suitable for the application requirements in terms of switching frequency, LED current accuracy and temperature.


Figure. 15 Switching Frequency vs. Inductor Value
The inductor influences the LED current accuracy that the system is able to provide. The following section highlights how to select the inductor in relation to the device packages and the LED current, while maintaining the chip temperature below $+70^{\circ} \mathrm{C}$.

## Applications Information (cont.)



Figure. 16 Recommended Inductor with 1A LED Current

## Capacitor Selection

The small size of ceramic capacitors makes them ideal for AP8802H applications. X5R and X7R types are recommended because they retain their capacitance over wider voltage and temperature ranges than other types such as Z 5 U . A $2.2 \mu \mathrm{~F}$ input capacitor is sufficient for most intended applications of AP8802H.
A $4.7 \mu \mathrm{~F}$ input capacitor is suggested for application with an input voltage equal or higher than 60 V .

## Diode Selection

Schottky diodes, e.g. B2100 or B1100, with their low forward voltage drop and fast reverse recovery, are the ideal choice for AP8802H applications.

60V 1A LED STEP-DOWN CONVERTER

## Applications Information (cont.)

## LED Current Adjustment/Dimming

The LED current for the AP8802H can be adjusted by driving the CTRL with a digital signal (PWM dimming) or by driving the CTRL with a DC voltage between 0.3 V and 2.5 V ( DC dimming).

If the CTRL pin is driven by an external voltage (lower than 2.5 V ), the average LED current is:

$$
\mathrm{I}_{\mathrm{LED}}=\frac{\mathrm{V}_{\mathrm{CTRL}}}{\mathrm{~V}_{\mathrm{REF}}} \times \frac{\mathrm{V}_{\mathrm{THD}}}{R_{\mathrm{SET}}} \quad \text { where } \mathrm{V}_{\mathrm{REF}} \text { is nominally } 1.25 \mathrm{~V}
$$



Figure. 17 LED Current vs. $\mathrm{R}_{\text {SET }}$ and $\mathrm{V}_{\text {CTRL }}$

Figure 17 shows that reducing the CTRL voltage by a factor of 2 also reduces the LED current by a factor of 2 . The AP8802H has the ability vary the LED current by a factor of 2 above the default value set by $R_{\text {SET }}$ down to a factor of 0.24 of the nominal LED current. This provides an 8.33:1 dynamic range of the DC dimming.

A low pass filter (pole frequency $\sim 500 \mathrm{kHz}$ ) on the CTRL pin of the AP8802H automatically provides some soft-start function of the LED current on initial start-up (this phenomenon can be seen in Figure 7); the built in soft-start period can be increased by the addition of an external capacitor onto the CTRL pin.

The AP8802H's dimming range can be increased above this DC dimming factor by applying a PWM signal to the CTRL pin using this method dimming dynamic ranges above 100 can be achieved.

## Applications Information (cont.)

## PWM Dimming of LED Current

When a low frequency PWM signal with voltages between 2.5 V and a low level of zero is applied to the CTRL pin the output current will be switched on and off at the PWM frequency. The resultant LED current $\mathrm{I}_{\text {LEDavg }}$ will be proportional to the PWM duty cycle. See Figure 6.
A Pulse Width Modulated (PWM) signal with a max resolution of 8 -bit, can be applied to the CTRL pin to change the output current to a value above or below the nominal average value set by resistor RSET.

To achieve this resolution the PWM frequency has to be lower than 500 Hz . The ultimate resolution will be determined by the number of switching cycles required to get back to nominal LED current once the PWM voltage is high relative to PWM frequency. Lower switching frequencies and higher PWM frequencies will result in lower PWM dimming dynamic ranges.


Figure. 18 Low Frequency PWM Operating Waveforms

There are different ways of accomplishing PWM dimming of the AP8802H LED current:

## Directly Driving CTRL Input

A Pulse Width Modulated (PWM) signal with duty cycle DPWM can be applied to the CTRL pin to adjust the output current to a value above or below the nominal average value set by resistor $\mathrm{R}_{\text {SET }}$. When driving the CTRL with a voltage waveform care should be taken not to exceed a drive voltage of 2.5 V (where extra brightness is required) or 1.25 V if a maximum of $100 \%$ brightness is required.

A way of avoiding over-driving the CTRL pin is use an open collector/drain driver to drive the CTRL pin.

## Driving the CTRL Input via Open Collector Transistor

The recommended method of driving the CTRL pin and controlling the amplitude of the PWM waveform is to use a small NPN switching transistor. This uses the internal pull-up resistor between the CTRL pin and the internal voltage reference to pull-up CTRL pin when the external transistor is turned off.

## Driving the CTRL Input From a Microcontroller

If the CTRL pin is driven by a MOSFET (either discrete or open-drain output of a micro-controller) then Schottky diode maybe be required due to high Gate / Drain capacitance, which could inject a negative spike into CTRL input of the AP8802H and cause erratic operation but the addition of a Schottky clamp diode (eg Diodes Inc. SD103CWS) to ground and inclusion of a series resistor (3.3k) will prevent this.

## Applications Information (cont.)

## Soft-Start

An external capacitor from the CTRL pin to ground will provide a soft-start delay, by increasing the time taken for the voltage on this pin to rise to the turn-on threshold and by slowing down the rate of rise of the control voltage at the input of the comparator. Adding capacitance increases this delay by approximately $200 \mu \mathrm{~s} / \mathrm{nF}$. The graph below shows the variation of soft-start time for different values of capacitor.


## Thermal Considerations

The graph below in Figure 19, gives details for power derating. This assumes the device to be mounted on a $25 \times 25 \mathrm{~mm}$ PCB with $10 z$ copper standing in still air.


Figure. 19 AP880H Derating Curve

AP8802H
60V 1A LED STEP-DOWN CONVERTER

## Applications Information (cont.)

## Fault Condition Operation

The AP8802H has by default open LED protection. If the LEDs should become open circuit the AP8802H will stop oscillating; the SET pin will rise to $\mathrm{V}_{\mathrm{IN}}$ and the SW pin will then fall to GND. No excessive voltages will be seen by the AP8802H.
If the LEDs should become shorted together the AP8802H will continue to switch however the duty cycle at which it will operate will change dramatically and the switching frequency will most likely decrease. The on-time of the internal power MOSFET switch will be significantly reduced because almost all of the input voltage is now developed across the inductor. The off-time will be significantly increased because the reverse voltage across the inductor is now just the Schottky diode voltage (See Figure 20) causing a much slower decay in inductor current. During this condition the inductor current will remain within its controlled levels and so no excessive heat will be generated within the AP8802H.


Fig. 20 Switching Characteristics (normal open to short LED chain)

## Ordering Information


(3)

| Device |  | 13" Tape and Reel |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | Packaging <br> (Note 11) | Quantity | Part Number Suffix |
| AP8802HSP-13 | SP |  | 2500/Tape \& Reel | -13 |

Note: 11. Pad layout as shown on Diodes Inc. suggested pad layout document AP02001, which can be found on our website at http://www.diodes.com/datasheets/ap02001.pdf.

## Marking Information

SO-8EP

## ( Top View)



## Package Outline Dimensions (All Dimensions in mm)

## SO-8EP



| SO-8EP (SOP-8L-EP) |  |  |  |
| :---: | :---: | :---: | :---: |
| Dim | Min | Max | Typ |
| A | 1.40 | 1.50 | 1.45 |
| A1 | 0.00 | 0.13 | - |
| b | 0.30 | 0.50 | 0.40 |
| C | 0.15 | 0.25 | 0.20 |
| D | 4.85 | 4.95 | 4.90 |
| E | 3.80 | 3.90 | 3.85 |
| E0 | 3.85 | 3.95 | 3.90 |
| E1 | 5.90 | 6.10 | 6.00 |
| e | - | - | 1.27 |
| F | 2.75 | 3.35 | 3.05 |
| H | 2.11 | 2.71 | 2.41 |
| L | 0.62 | 0.82 | 0.72 |
| N | - | - | 0.35 |
| Q | 0.60 | 0.70 | 0.65 |
| All Dimensions in | mm |  |  |

## Suggested Pad Layout

SO-8EP


| Dimensions | Value <br> (in mm) |
| :---: | :---: |
| $\mathbf{C}$ | 1.270 |
| $\mathbf{X}$ | 0.802 |
| $\mathbf{X 1}$ | 3.502 |
| $\mathbf{X 2}$ | 4.612 |
| $\mathbf{Y}$ | 1.505 |
| Y1 | 2.613 |
| $\mathbf{Y 2}$ | 6.500 |

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